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continuous and discrete signals are defined as $E_{\infty} = \int_{-\infty}^{\infty} |x(t)|^2 dx$ and $E_{\infty} = \sum_{n=-\infty}^{\infty} |x[n]|^2$, and $P_{\infty} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dx$ and $P_{\infty} = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x[n]|^2$. Using these we can compute each part of the given problem. Part (a): For this signal we find E_{∞}

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$$\begin{aligned} &= \int_0^{\infty} 0 \cdot e^{-4t} dt = e^{-4t} \\ &-4 \int_0^{\infty} 0 = 1/4, \text{ and } P_{\infty} \\ &= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_0^T 0 \\ &e^{-4t} dt = \lim_{T \rightarrow \infty} \end{aligned}$$

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shown in Fig. 1 in terms of unit step functions. Fig. 1

Answer $x(t) = u(t-1) + 2u(t) - u(t-1) - u(t-2) - u(t-3) + 2$.

Consider the system shown in Fig. 2.

Determine whether it is (a) memoryless, (b) causal, (c) linear, (d) time-invariant, or (e) stable. Fig. 2 (a) From Fig. 2 we have $y(t) = T \{ x(t) \} = x(t) \cos Z \dots$

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